

EL977166363US

**HIGH PERFORMANCE IMPLEMENTATION OF EXPONENT ADJUSTMENT  
IN A FLOATING POINT DESIGN**

TECHNICAL FIELD

The invention relates generally to floating point units (FPUs) and, more particularly, to a floating point unit that  
5 calculates exponent values within exponent logic.

BACKGROUND

The calculation of a floating point within processing systems is an important part of numerical calculation.  
10 Floating point calculation can be generally defined as the computation of a number that potentially has meaningful values to the right of a decimal point. There are a number of ways to represent and calculate floating point computations.

15 In the Institute for Electronics and Electrical Engineers (IEEE) 754 Binary Floating Point Standard, a floating point number is represented as sign, exponent and fraction. The exponent is represented as a biased binary value. In other words, the exponent "e" is the binary value  
20 of "E" minus a pre-defined bias. This can be represented mathematically as the value(E) = binary\_value(E) - bias. For n-bit exponents, the bias value is  $(2^{(n-1)}-1)$ . For instance, for an 8-bit exponent of a single precision number, the bias is 127.

25 FPU design is split into an exponent data path and a fraction data path. The input into a fraction adder of the fraction data path is in the form of A times B plus C. The exponent data path conveys the exponents Ea, Eb and Ec into an exponent logic.

30 In conventional FPUs, there is generated an exponent value from exponent logic. Depending on the exponent

difference of addend and product, and some sign information as calculated within the fraction adder and conveyed over a select product line, this exponent either is the exponent of the addend ( $E_c$ ), the exponent of the product ( $E_a + E_b - \text{bias}$ ),  
5 or the exponent of the product plus an offset ( $E_a + E_b + \text{delta}$ ).

Thus, based on the exponent difference, multiplexers select three values  $E_x$ ,  $E_y$ ,  $E_z$ , which, when added together, give the appropriate exponent. These three values are input into a 3:2 compressor, thereby generating a carry and a sum.  
10 The carry and the sum are then added together in a 2:1 adder. This summed value is then conveyed to an Exponent Adjust and Rounding logic (EAD). This summed value is the value "e." The summed value is the exponent corresponding to the unrounded fraction provided by the adder in the fraction  
15 data path. The EAD logic adjusts the exponent based on the normalization shift amount and performs the exponent rounding.

Within the FPU calculator, there is also something called a "leading zero anticipator" (LZA). The LZA  
20 generates an estimate of the number of leading zeroes in the result of the fraction adder. In other words, while the exponent logic determines the addition of received exponent values  $E_a$ ,  $E_b$  and  $E_c$ , the LZA predicts the number of zeros that are going to occur as "leading zeros" within the  
25 addition process of the fraction adder. However, this is only a prediction, and the prediction of the LZA can be one more than it should be. Whatever the result, the output of the LZA is subtracted from the output of the 2:1 adder of the exponent logic (the value "e") and a first possible  
30 value, "e2", is generated.

As discussed previously, due to the nature of the LZA estimation, the exponent "e2" using the estimate from the LZA can be one count lower than the exponent should be if

the count of the LZA were to accurately reflect the number of leading zeros. Therefore, the EAD calculates the exponent based on both the possible values of the actual number of leading zeros. For instance,  $e2=e-lza$  and  $e2=e-lza+1$ . Meanwhile, both the output of the LZA and the fraction adder are input into an LZA correction circuit. The LZA correction circuit then sends a signal, `lza_corr`, to the EAD that signifies whether or not to use the higher or lower exponent number in the EAD. The EAD uses the `lza_corr` to select one of the two possible `e2` values. In other words, the selected value becomes the final `e2` value.

Meanwhile, and substantially in parallel, a normalizer-rounder circuit receives as input the output of the fraction adder and the output of the LZA. The normalizer takes a received calculated value of an arbitrary number of floating point precision, such as 128 bits, and "normalizes" it, shifting out the leading zeros. The rounder rounds the normalized fraction to a standard format of "x" number of bits, such as 23 bits for single precision. The rounding of the exponent is done in EAD.

Furthermore, within the EAD, after the selection of the correct `e2` value (which occurs after receiving the `lza_corr` value from the `lza_correction` signal from the LZA correction circuit), the FPU tests for overflow, underflow or special values, such as NAN and Infinity (this is part of the exponent rounding). Typically, `e2` is compared to both an "emax" value and an "emin" value (these values are constants), and overflow and underflow signaling values are generated therefrom. These overflow and underflow signaling values are incorporated into a result select signal generated by the EAD. The result select signal signifies whether `e2` (and the normalized rounded fraction) is a valid value or, alternatively, whether an underflow or overflow

has occurred or whether a special result (NaN, infinity, zero) is to be chosen. The result select signal and the e2 value are input into the result MUX. The result MUX selects between the regular rounded result, and some special values, such as Infinity, NaN, Zero. This selection is done based on the result select signal provided by EAD.

From the EAD to the result MUX, one of four different values are given within the result select signal. If the signal is overflow, underflow, or special value, the e2 signal is not to be used. If neither of these conditions apply, the result generator uses the e2 value and combines with the normalized output of the normalizer/rounder to create a final floating point sum generated as a standardized floating point value as a function of the result signal, the EAD e2 value, and the normalizer/rounder.

There are different kinds of rounding that can be performed by the rounder. In a fully IEEE compliant FPU, the design supports four rounding modes. The four rounding modes are a rounding up or down to the closest representable value mode, always rounding towards zero (for both positive and negative numbers), always rounding towards plus infinity (that is, to the higher value for both positive and negative values), and always rounding down towards the negative infinity (that is, to the smaller value for both positive and negative values). During the rounding step, the rounder and EAD together check for exception conditions, such as Overflow, Underflow and Inexact result indicia. Illegal operation exception and divide by zero get detected very early in the pipeline. In other words, there are two more IEEE exceptions, but they are not detected by the rounder and EAD; they can be detected based on the inputs within the first couple of cycles.) In case of denormal results (which have a 0 in front of the binary point and come only with the

smallest possible exponent), modifications of the normalization and rounding are required. Depending on the design, this is either done on the fly while passing the data through LZA, normalizer and rounder, or extra cycles  
5 are added in order to adjust the result.

The FPU is either in IEEE mode, which means the result is fully IEEE compliant, or the FPU only supports parts of the IEEE standard in order to improve the performance of the FPU. In order to improve the performance of the floating-  
10 point operations, some design only supports part of the IEEE standard, that is, the design only implements one rounding mode and denormal results are forced to zero. High-performance real-time graphics applications are tuned to use the simplest of the IEEE rounding modes: round towards zero,  
15 also known as truncation. Such a fast FPU mode with truncation rounding is very appealing because the fraction rounding is reduced to truncating the fraction, whereas the other three IEEE rounding modes require an incrementer in the rounder which increments the fraction. Thus, a fast mode  
20 with truncation speeds up the rounding step.

However, there is a problem with prior art fast mode calculations which comprise truncation rounding. There can be significant processing time in calculating the exponents "e2" based on exponent "e" and the output LZA value,  
25 performing an LZA correction to determine the final value of "e2," and checking for overflow and underflow conditions. When supporting all four IEEE rounding modes, the time to run the EAD e2 calculations as a function of the LZA, and correcting the lza\_corr and the overflow/underflow check,  
30 may not be an issue, as the normalizer and rounder takes time to perform its intensive calculation. However, in fast mode, there is no rounder used on the fraction path just the normalizer. Under this condition, the processing time of

the EAD can be a bottleneck.

Therefore, there is a need for an FPU system designed for operation in fast mode that addresses at least some of the disadvantages associated with conventional FPU systems  
5 designed to operate in fast mode.

#### SUMMARY OF THE INVENTION

The present invention provides for a floating point unit (FPU) which generates a correction signal and an  
10 inverted leading zero signal. Exponent logic is configured to generate an exponent value, a first incremented exponent value, and a second incremented exponent value. Exponent adjust and rounding logic is configured to receive the exponent value, the first incremented exponent value, and  
15 the second incremented exponent value. The exponent adjust and rounding logic is further configured to add the inverted leading zero signal to the first incremented exponent value and the second incremented exponent value, thereby producing an exponent output value, a first incremented exponent  
20 output value, and a second incremented exponent output value.

#### BRIEF DESCRIPTION OF THE DRAWINGS

25 For a more complete understanding of the present invention, and the advantages thereof, reference is now made to the following Detailed Description taken in conjunction with the accompanying drawings, in which:

FIGURE 1 schematically depicts a prior art FPU system;  
30 and

FIGURE 2 illustrates an FPU with exponent logic and an EAD with a plurality of exponent values configured to be input into the EAD.

DETAILED DESCRIPTION

In the following discussion, numerous specific details are set forth to provide a thorough understanding of the present invention. However, those skilled in the art will appreciate that the present invention may be practiced without such specific details. In other instances, well-known elements have been illustrated in schematic or block diagram form in order not to obscure the present invention in unnecessary detail. Additionally, for the most part, details concerning network communications, electro-magnetic signaling techniques, and the like, have been omitted inasmuch as such details are not considered necessary to obtain a complete understanding of the present invention, and are considered to be within the understanding of persons of ordinary skill in the relevant art.

In the remainder of this description, a processing unit (PU) may be a sole processor of computations in a device. In such a situation, the PU is typically referred to as an MPU (main processing unit). The processing unit may also be one of many processing units that share the computational load according to some methodology or algorithm developed for a given computational device. For the remainder of this description, all references to processors shall use the term MPU whether the MPU is the sole computational element in the device or whether the MPU is sharing the computational element with other MPUs, unless otherwise indicated.

It is further noted that, unless indicated otherwise, all functions described herein may be performed in either hardware or software, or some combination thereof. In a preferred embodiment, however, the functions are performed by a processor, such as a computer or an electronic data processor, in accordance with code, such as computer program

code, software, and/or integrated circuits that are coded to perform such functions, unless indicated otherwise.

Turning to FIGURE 1, disclosed is a prior art FPU system 100 implementing a fused multiply-add  $A*B+C$ . A multiplier 105 receives the fractions of the values A and B, which are  $F_a$  and  $F_b$ , and computes the product  $F_a * F_b$ . An aligner 108 receives the fraction  $F_c$  of value C and the exponents of A, B and C, which are  $E_a$ ,  $E_b$ , and  $E_c$ ; the aligner aligns the fraction  $F_c$  relative to the fraction of the product. The outputs of the multiplier and aligner are provided to the adder 125 and the LZA 120. An exponent logic 110 receives the exponent values  $E_a$ ,  $E_b$ , and  $E_c$ . Within the exponent logic there is generated an exponent value "e". Depending on the exponent difference of addend and product and the sign/carry information from the fraction adder, this exponent either is the exponent of the addend ( $E_c$ ), the exponent of the product minus bias ( $E_a + E_b - \text{bias}$ ), or the exponent of the product plus an offset ( $E_a + E_b + \text{delta}$ ).

The exponent value "e" is sent to an EAD 130. Within the EAD, there is received an "estimated shift amount LZA" from a leading zero anticipator 120. Within the EAD 130, both values  $e2a = \text{exponent} - \text{LZA}$  and  $e2b = \text{exponent} - \text{LZA} + 1$  are computed.

Meanwhile, an LZA corrector 140 has also received the estimated shift amount LZA value from the LZA 120 and the output of the fraction adder 125. The LZA correction 140 detects whether the number of leading zeros computed by LZA is correct or off by one, and then inputs this as an `lza_corr` signal to the EAD 130. Based upon the `lza_corr` value, the EAD 130 selects the final `e2` value, which is sent to a result generator 160. The EAD 130 also generates a result select signal which is input into the result generator 160. The result signal indicates whether the



result generator 160 should output as a final floating point value from a rounder 150, which is a combination of the e2 value and the normalized and rounded output of the normalizer/rounder 150. Alternatively, the results select  
5 signal can indicate an underflow, an overflow, or output from special cases and operands logic 155. In any event, the result is output as the final floating point value from the result generator 160.

Turning now to FIGURE 2, illustrated is an FPU exponent  
10 system 200. More particularly, illustrated is an exponent logic 220 coupled to an EAD 230. Generally, the system 200 calculates the alternative exponents within the exponent logic 220 and instead generates three exponent values for use by the EAD 230, not one (the value "e", as is  
15 illustrated in FIG. 1). The three values are a result of a 3:2 addition (corresponding to the value "e" from FIG. 1), plus one value higher and two values higher.

In FIGURE 2, the exponent logic 220 receives the Ea, Eb, Ec, and some sign/carry information from the fraction  
20 adder into an exponent operand selection 212. The Exponent logic 220 uses these values to generate Ex, Ey, and Ez values which is done in the same way as in a conventional design. The Ex, Ey and Ez values are input into a 3:2 compressor 221. Ez is a 10-bit string, but the 3:2  
25 compressor 221 is only eight bits wide. Thus, the two most significant bits of Ez, i.e. Ez[0:1], bypass the 3:2 compressor 221 and are fed directly into a 3-way compound adder 108 as sum(0:1). In the following and the preceding, the most significant bit is bit 0.

30 The 3:2 compressor 221 generates the sum (2:9) and the carry values (1:8). Generally, the processing that has gone before this stage in FIGURE 2 is similar as in FIGURE 1. However, in the FPU system 200, three values are generated

from the addition of the sum and the carry. These three values are sent to the EAD 230. The three values are  $S_0$ , (the addition, equivalent to the value "e" of FIG. 1),  $s_1$  (the addition plus one, "e+1"), and  $s_2$  (the addition 'e plus two' "e+2"). Using a 3-way compound adder 225, the three sums (sum, sum+1 and sum+2) can be generated without additional delay.

Turning back to FIGURE 1, the exponent logic 110 would generate "e" and then the EAD 130 generates  $e-lza$  and  $e+1-lza$  or it generates "e" and  $e+1$ , selects  $e'$  between them and then computes  $e_2=e'-lza$ , and a selection between these values would be made by the EAD 130 as a function of the  $lza\_corr$  value received from the LZA correction logic 140. Turning back to FIGURE 2,  $e$ ,  $e+1$  and  $e+2$  are generated within the exponent logic 220. Furthermore, their use differs from the use of "e" of FIG. 1.

In the FPU system 200, "not lza" (!lza) is used. Using !lza is one way to perform subtraction within a logic circuit. For instance,  $a-b=a+!b+1$ . Instead of computing  $e=ea+eb-bias$  and  $e_2=e+!lza+1$  within the EAD 130,  $S_1=ea+eb-bias+1$  is computed within the exponent logic 220 and EAD then computes  $E_2=S_1+!lza$ . This saves the carry-in input in the adder, further reducing the delay of the EAD circuit. The computation of "e" and  $e+1$  as well as the increment (+1) which is needed for the subtraction of lza are performed by the compound adder 225 in the exponent logic 220. Thus, this computation is moved to a prior clock cycle as compared to a conventional FPU, speeding up the subtraction in EAD 230.

Within the EAD 230, two values  $e_{2a}$  and  $e_{2b}$  are generated for the exponent  $e_2=e-lz$ , where  $lz$  is the exact number of leading zeros. Due to the nature of logical arithmetic,  $e-lza = e_{2a}$ , which equals  $e+!lza+1 = S_1+!lza$  as performed within the adder 236.  $E_{2b}=e-lza+1 =$

$e+!lza+2=S2+!lza$ , as performed within an adder 234. Therefore,  $S1=e+1$ ;  $S2=e+2$ . Thus, the outputs  $S1$  and  $S2$  of the exponent logic are added to the  $!lza$  value within the add (10b) 234, 236 of EAD 230 to generate  $e2a$  and  $e2b$ . The  
5 two most significant bits of both values are sent to a result MUX selects circuit 240, and both of these values are sent to a result generator (not shown) and selected by a result generator as a function of the selects output of the result MUX selects generator 240.

10 In FIGURE 1, in order to check for exception conditions, the final  $e2$  was calculated within the EAD 130. The EAD 130 performs the overflow and underflow checking after that. System 200 avoids this latency by performing the exception checking substantially in parallel with the  
15 calculations of  $e2a$  and  $e2b$ ; both calculations are performed by EAD 230. In the system 200, the LZA might overestimate the number of leading zeros by one. (In other designs the LZA might underestimate the number. With a slight  
modification, our invention also works for that case).

20 Turning back to FIGURE 1, the exponents, the  $ea$ ,  $eb$ ,  $ec$  values, are input into the exponent logic 110 are in 8-bit biased format, as referenced in the IEEE Standard for Binary Floating-Point Arithmetic. The intermediate results in the exponent calculation exceed the range of 8-bit biased binary  
25 values. There are several different formats for the 10-bit intermediate results. These intermediate results are the exponent " $e$ " of FIG. 1 as well as  $e+1$ ,  $e-lza$ . For FIG. 2, the intermediate results are the vectors CARRY, SUM,  $S0$ ,  $S1$ , and  $S2$ . One most common format being 10-bit biased binary  
30 values, that is, the numbers have 10 bit representations and the bias is 511 instead of 127.

Turning again to FIGURE 2, the system 200 uses a different representation for the intermediate exponent

results  $S_0, S_1, S_2$ . The intermediate numbers  $S_0, S_1$ , and  $S_2$  are represented as 10-bit two's complement numbers with a bias of 127. This helps with the underflow detection.  $e=00000001$  corresponds to the value  $1-127=-126$ . An underflow  
5 occurs when the exponent becomes smaller than -126. In one embodiment, overflow and underflow detection are performed as follows.

Specifically, due to the logical arithmetic nature of underflow detection,  $e_{2a}$  is less than  $e_{min}$  if, and only if,  
10 the value of  $e_{2a}$  is less than the value of -126. In an embodiment of a 10-bit two's complement numbers with a bias of 127, this is the case if and only if the (unbiased) two's complement value of  $e_{2a}$  is less than 1. In other words, if the two's complement value of exponent  $e_{2a}$  is zero or  
15 negative or, alternatively, if  $e_{2a}-1$  is negative, there is an underflow.

Within the underflow, both  $e_{2a}$  and  $e_{2b}$  checking is performed. This is performed within the EAD 230. For the underflow detection of  $e_{2a}$ , it is checked whether  $e_{2a}-1 < 0$ .  
20  $S_0$  is added to  $!lza$  within an adder 238 to perform this test ( $e_{2a}-1 = S_1+!lza-1=S_0+!lza$ ). If the sign of  $e_{2a}-1$  is 1, then there is an underflow for  $e_{2a}$ . For any value greater than or equal to 0, the sign will equal zero. The sign bit of the addition  $S_0+!lza$  indicates that  $e_{2a}$  is less than  
25  $e_{min}$ . In the system 200, this signal is displayed as  $e_{2a\_lt\_emin}$ .

In order to detect that  $e_{2b}$  causes an underflow, it is checked whether  $e_{2b}-1=e_{2a}$  is less than 0. This can be detected by inspecting the sign bit of the  $e_{2a}$  result. An  
30 underflow occurs for  $e_{2b}$  if the sign bit  $e_{2a}(0) = e_{2b\_lt\_emin}$  is 1. Both of these results ( $e_{2a\_lt\_emin}$ ,  $e_{2b\_lt\_emin}$ ) are also input into a result mux selects logic 240. One advantage of this approach is that the underflow

condition can be determined *before* receiving the `lza_corr` value within the result mux selects 240, which can save significant time. An advantage of using the 10-bit two's complement representation with bias 127 in the adder 238 is  
5 that the underflow can be detected by checking the sign bit.

Within an overflow selector, there is a testing of an overflow condition. This is performed as follows. Exponent `e2a` causes an overflow, if it is larger than the maximal exponent `emax`. `Emax` is the constant value 127. In the number  
10 representation used within FIGURE 2 (10-bit two's complement with bias 127), `Emax` has the representation "00.1111.1110". Thus, exponent `e2a` causes an overflow if and only if `e2a+1 > 00.1111.1111`. This is true if and only if `e2b = e2a+1` is greater or equal to 01.0000.0000. Due to the two's  
15 complement representation, the overflow of `e2a` can be checked by inspection of the two most significant bits of `eb2` for the pattern "01". Thus, `e2a_gt_emax = !e2b(0) and e2b(1)`. This computation is performed in the result mux select logic 240.

20 `S2 + !lza` is performed in the adder 234. Exponent `e2b=s2 + !lza` (as has already been outputted in the `e2b` output line) causes an overflow if it is larger than `emax`. Given the chosen number format, `e2b` causes an overflow if and only if `e2b` is greater or equal to 00.1111.1111. This  
25 can be checked by testing whether `e2b>00.1111.1111` or `e2b=00.1111.1111`. The first part of the test (check for greater than) is identical to the overflow check of `e2a`. For the second part of the test, in order for the comparison `e2b=00.1111.1111` to take place, however, it is not necessary  
30 for there to be a full calculation of `e2b`. Instead, the `s2` value and the `!lza` values are compared.

For single precision, the adder result is less than 100 bits wide. Therefore, the number of leading zeros is less

than 127 and hence, !lza has at least two leading ones. For the check  $e2b=00.1111.1111$ , is then determined whether  $!lza(0:9) + S2(0:9) = 100.1111.1111$  or  $00.1111.1111$ . The least significant eight bits of  $e2b$  are all One, if and only if  $S2(2:9)$  equals  $lza(2:9)$ . When adding these bits together, they do not generate a carry out. Given that  $!lza(0:1)=11$ , and that the sum of the less significant bits is not generating a carry,  $!lza(0:1) + S2(0:1)$  equals 100 if and only if  $S2(0:1)=01$ . Thus, comparator 232 detects that  $e2b=00.1111.1111$  by checking that  $S2(0:1)=01$  and that  $S2(2:9)$  equals  $lza(2:9)$ . This is indicated by a signal  $e2a\_eq\_emax$ .

Finally, the  $e2b(0:1)$  value, the  $e2a(0)=e2b\_lt\_emin$  value, the  $e2a\_eq\_emax$  value and the  $e2a\_lt\_emin$  value are all input into the result mux selects logic 240. In the system 200, the result mux selects logic 240 has five different output logic states. These are 10000 for number 0, 01000 for number 1, 00100 for number 2 and so on. The five outputs of the selector are as follows: if  $sel(0)$  is One, then a special/override value is generated, as input by the special case line and the result mux selects a special result. If  $sel(1)$  is One, then an overflow value is indicated and the result mux selects Infinity. If  $sel(2)$  is One, an underflow value is indicated and the result mux selects Zero. If  $sel(3)$  is One, then the result mux selects  $e2a$  and the values 1:23 of the output of the normalizer. If  $sel(4)$  is One, then the result mux selects  $e2b$  and the values 0:22 of the output of the normalizer.

spec	E2a-gt- emax	E2a-eg- emax	E2b-lt- emin	E2a-lt- emin	Lza-corr	Sel(0 :4)	Overflow/ underflow Exception	Result exponent
1						10000	Special	Special
0	1					01000	Overflow	127
0		1			1	01000	Overflow	127
0			1			00100	Underflow	0
0				1	0	00100	Underflow	0
0	0	0	0	0	0	00010	None	E2a
0	0	0	0	0	1	00001	None	E2b

TABLE 1: Logic of result mux generator 240.

The logic within the result mux selects generator 240  
 5 generates the select signals sel(0:4) and the exception  
 flags Overflow and Underflow according to the truth-table of  
 Table 1. In Table 1, a blank entry indicates that the value  
 is a "don't-care" in that particular case. Note that the  
 pair of signals e2a\_gt\_emax / e2a\_eg\_emax and the pair  
 10 e2b\_lt\_emin / e2a\_lt\_emin cannot be true (1) at the same  
 time.

If select spec is "on", then sel (0) is on, and no  
 further checking occurs. If signal spec is Zero, the result  
 mux selects logic 240 checks for an overflow or underflow  
 15 condition. Overflow occurs if e2a\_gt\_emax is on or if  
 e2a\_eg\_emax and lza\_corr is on. Underflow occurs if  
 e2b\_lt\_emin is on or if e2a\_lt\_emin is on and lza\_corr is  
 off.

It is understood that the present invention can take  
 20 many forms and embodiments. Accordingly, several variations  
 may be made in the foregoing without departing from the  
 spirit or the scope of the invention. The capabilities  
 outlined herein allow for the possibility of a variety of

programming models. This disclosure should not be read as preferring any particular programming model, but is instead directed to the underlying mechanisms on which these programming models can be built. The present invention is described for single precision numbers, but can easily be applied to other formats as well. The present invention is described for a fused multiply add FPU, but can also be applied to the add part of a split FPU design as well, for example.

10        Having thus described the present invention by reference to certain of its preferred embodiments, it is noted that the embodiments disclosed are illustrative rather than limiting in nature and that a wide range of variations, modifications, changes, and substitutions are contemplated  
15 in the foregoing disclosure and, in some instances, some features of the present invention may be employed without a corresponding use of the other features. Many such variations and modifications may be considered desirable by those skilled in the art based upon a review of the  
20 foregoing description of preferred embodiments. Accordingly, it is appropriate that the appended claims be construed broadly and in a manner consistent with the scope of the invention.